

Cartographic scale and minimum mapping unit influence in LULC Modelling

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<http://geofireg.ugr.es/sigeomod/?lang=en>



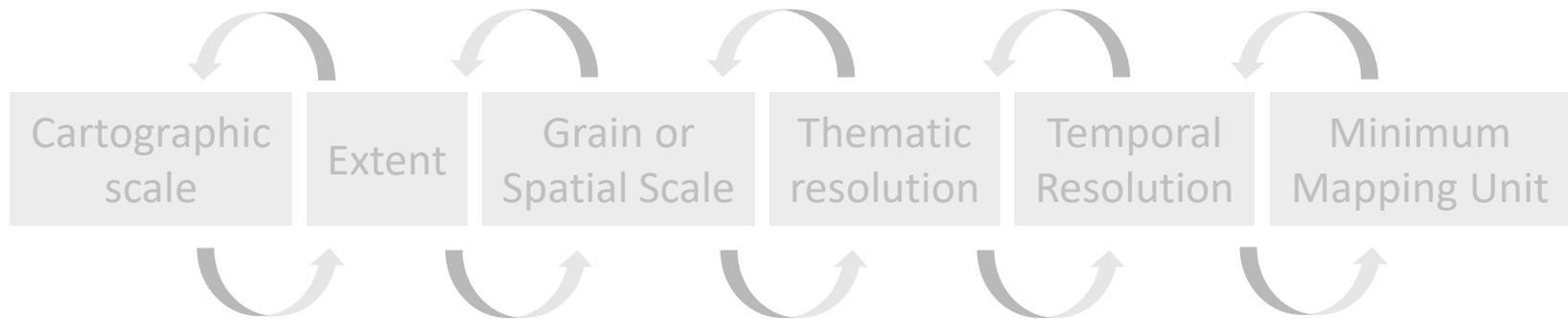
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GISTAM 2017. 27 April, 2017 - Porto

Geomatic approaches for modelling land change scenarios - GAMOLCS 2017

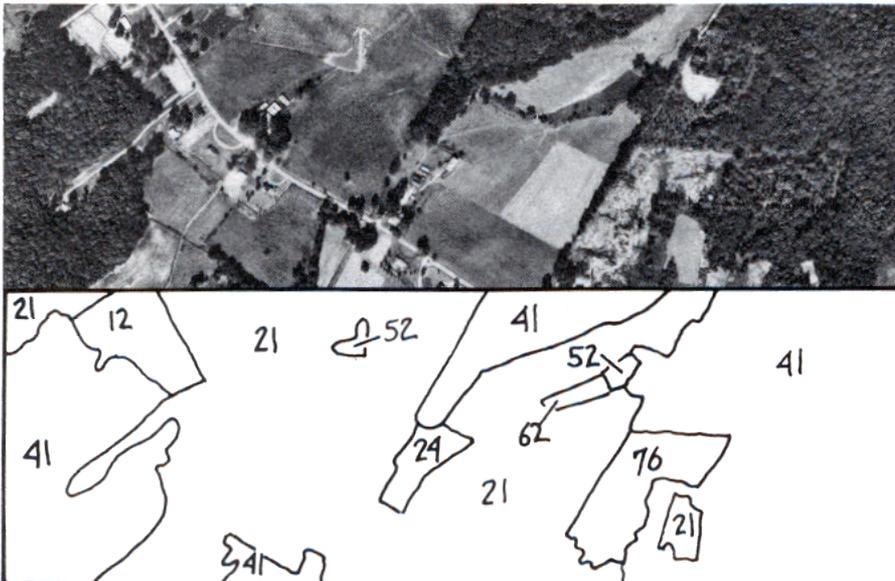
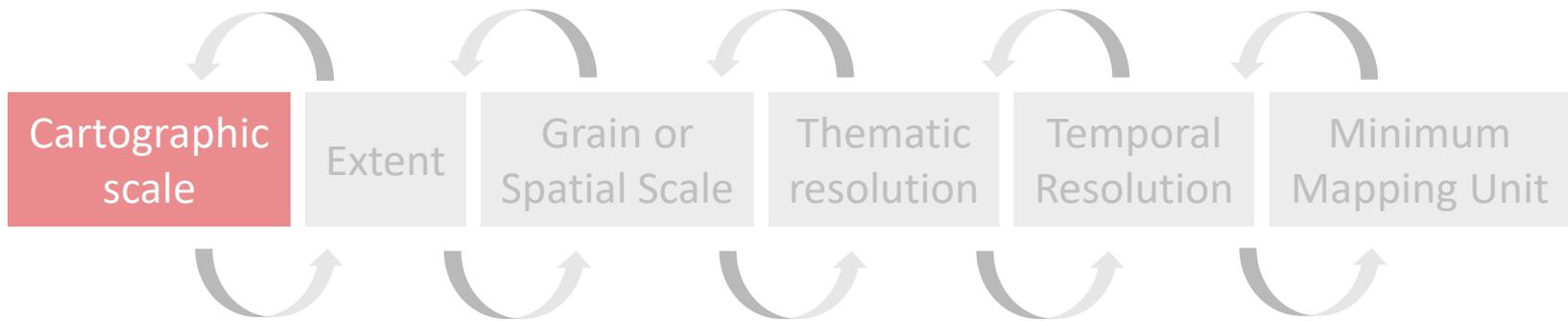
1 Background

What is the scale?



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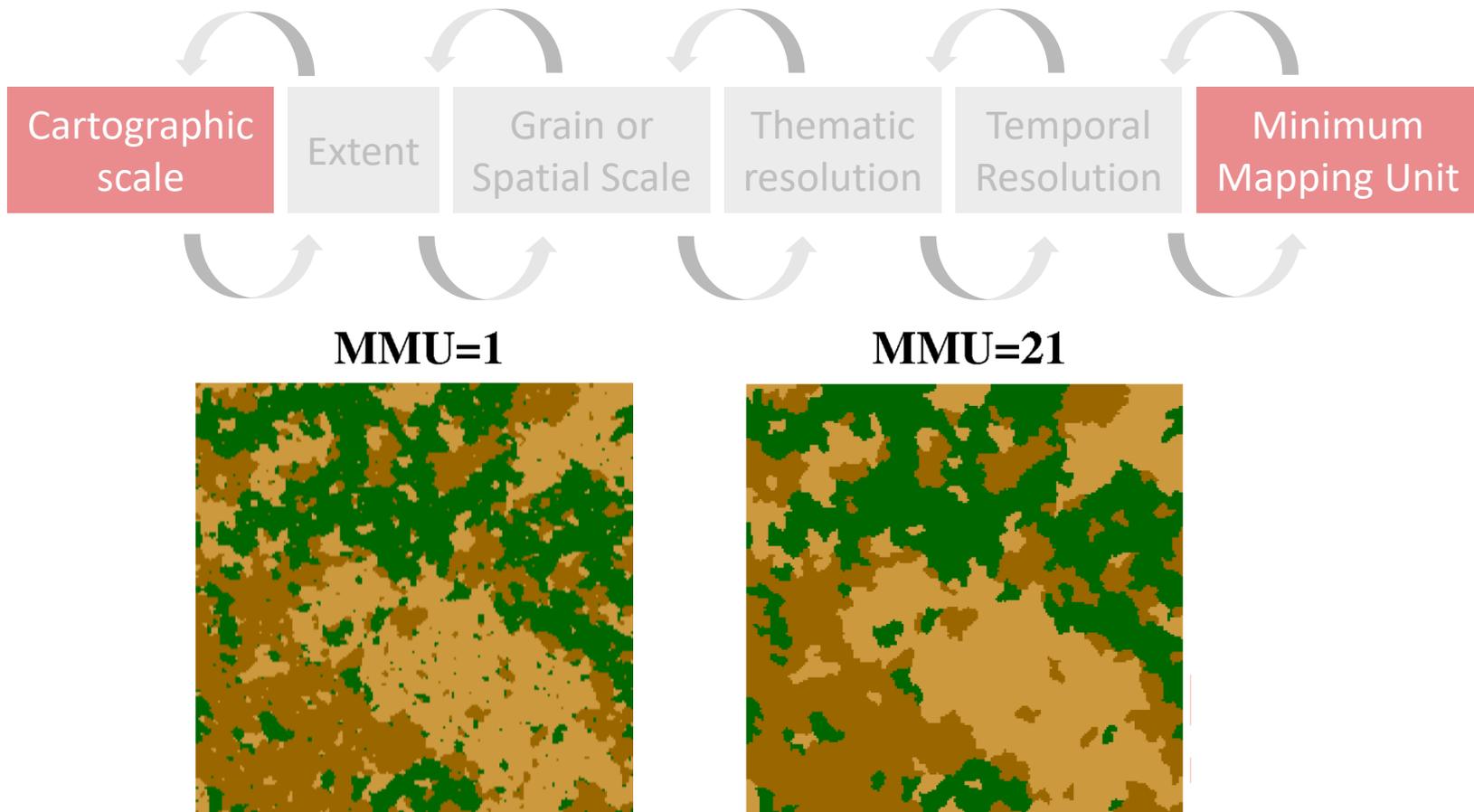


Source: www.geogra.uah.es



1 Background

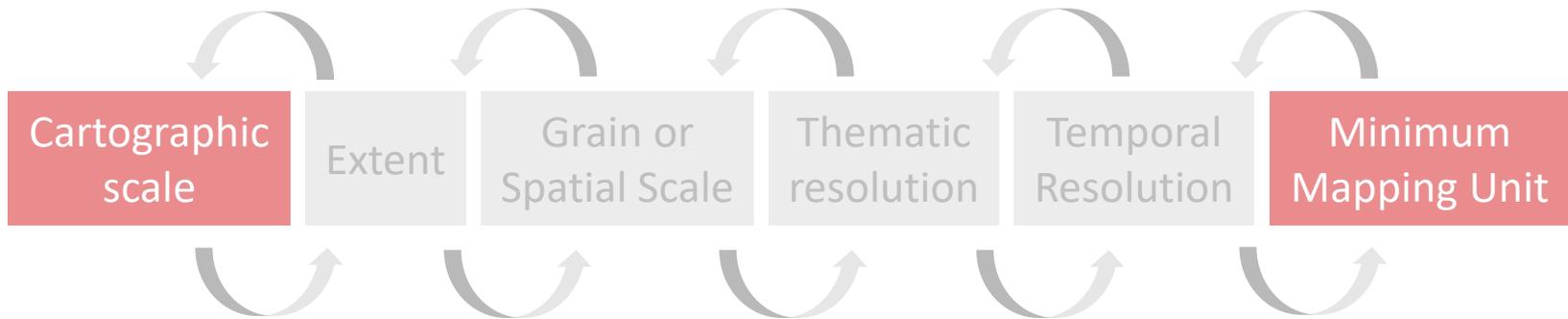
What is the scale?



Source: Saura, S. (2002). Effects of minimum mapping unit on land cover data spatial configuration and composition. *International Journal of Remote Sensing*, 23(22), 4853-4880.

1 Background

What is the scale?



2 Data Sets

SIOSE

1:25.000

MMU: 0.5-2ha

MMU Changes: 0.4ha

MMW: 15m (exceptions allowed)

Dates:

2005 – 2009 - 2011

Classification System

CORINE

1:100.000

MMU: 25h

MMU Changes: 5ha

MMW: 100m

Dates:

1990 – 2000 – 2006 - 2012

Description System

2 Data Sets

SIOSE

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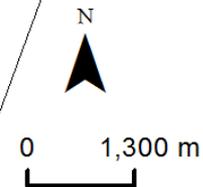
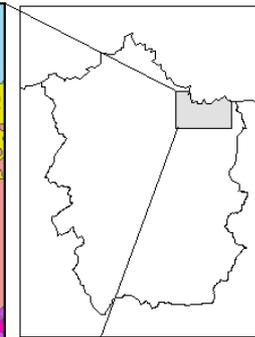
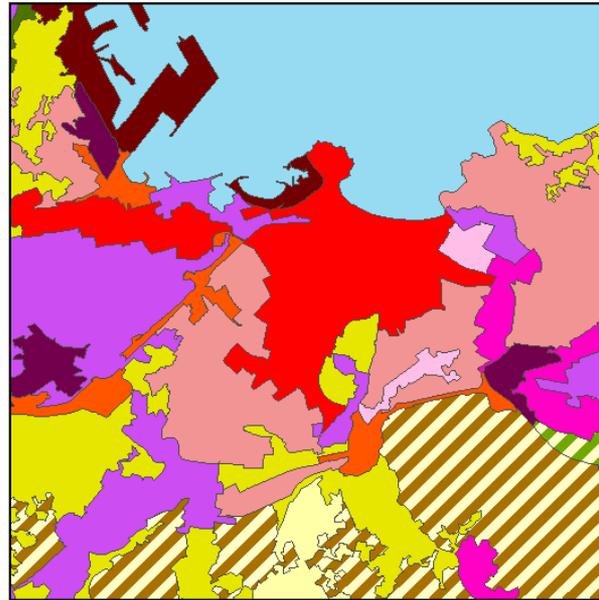
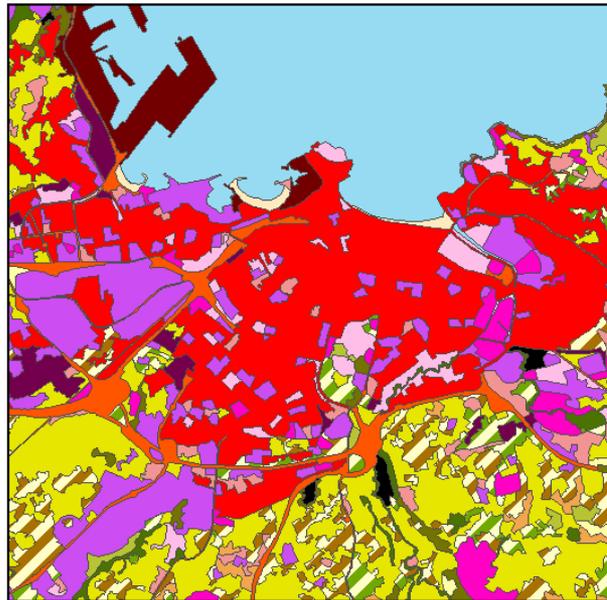
1990 – 2000 – 2006 - 2012

Description System

2 Data Sets

SIOSE

CORINE

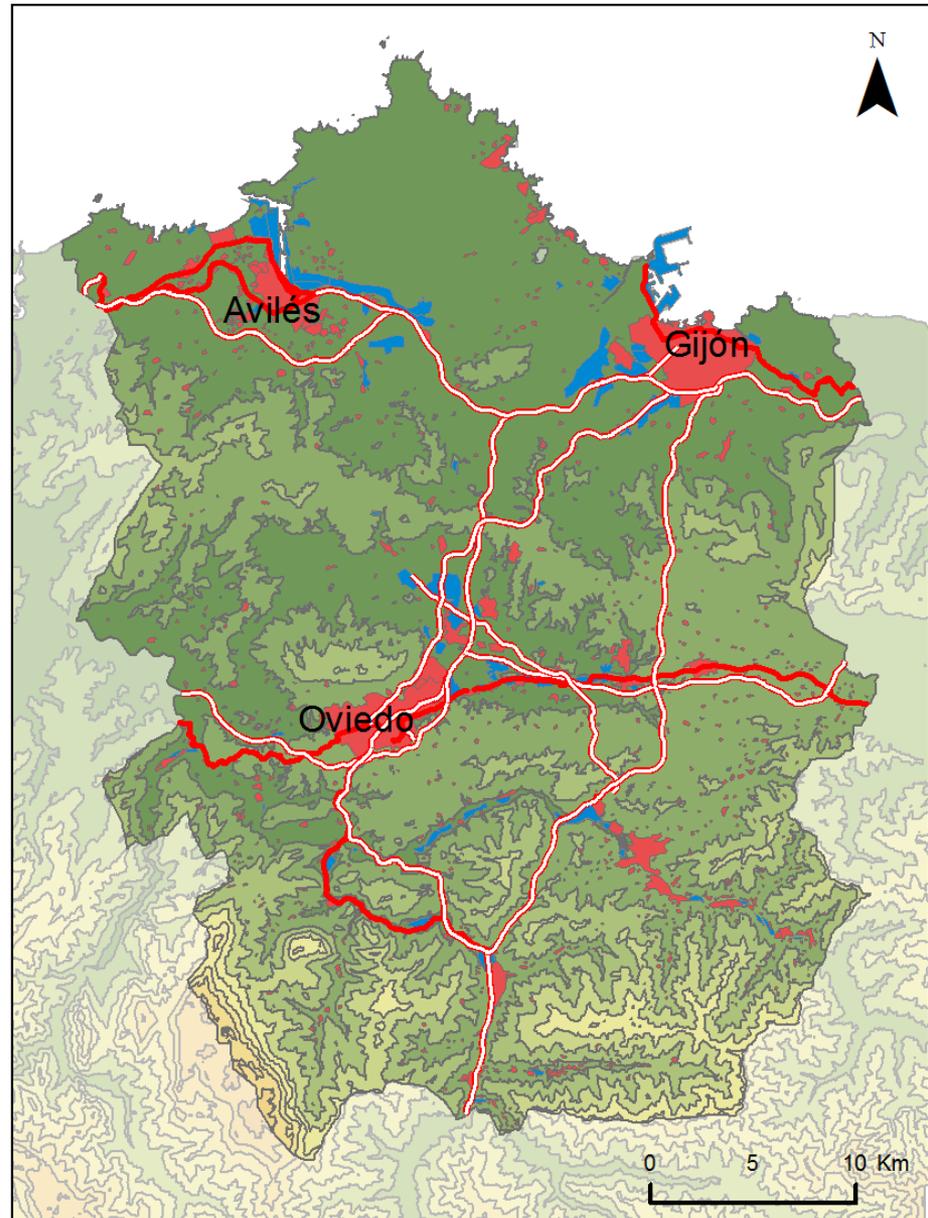
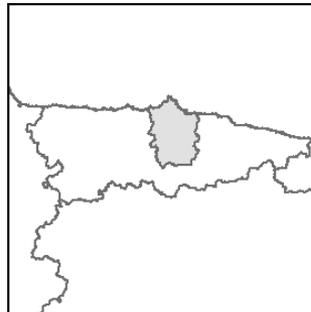


- | | | |
|--------------------------------|--|--------------------|
| Continuous urban fabric | Green urban areas | Forests |
| Discontinuous urban fabric | Sport and leisure facilities | Scrubland |
| Industrial or commercial units | Arable land | Natural grasslands |
| Road infrastructure | Fruit trees | Beaches |
| Port areas | Pastures | Bare rocks |
| Dump sites | Complex cultivation patterns | Marine water |
| Construction sites | Land principally occupied by agriculture | |

Study Area

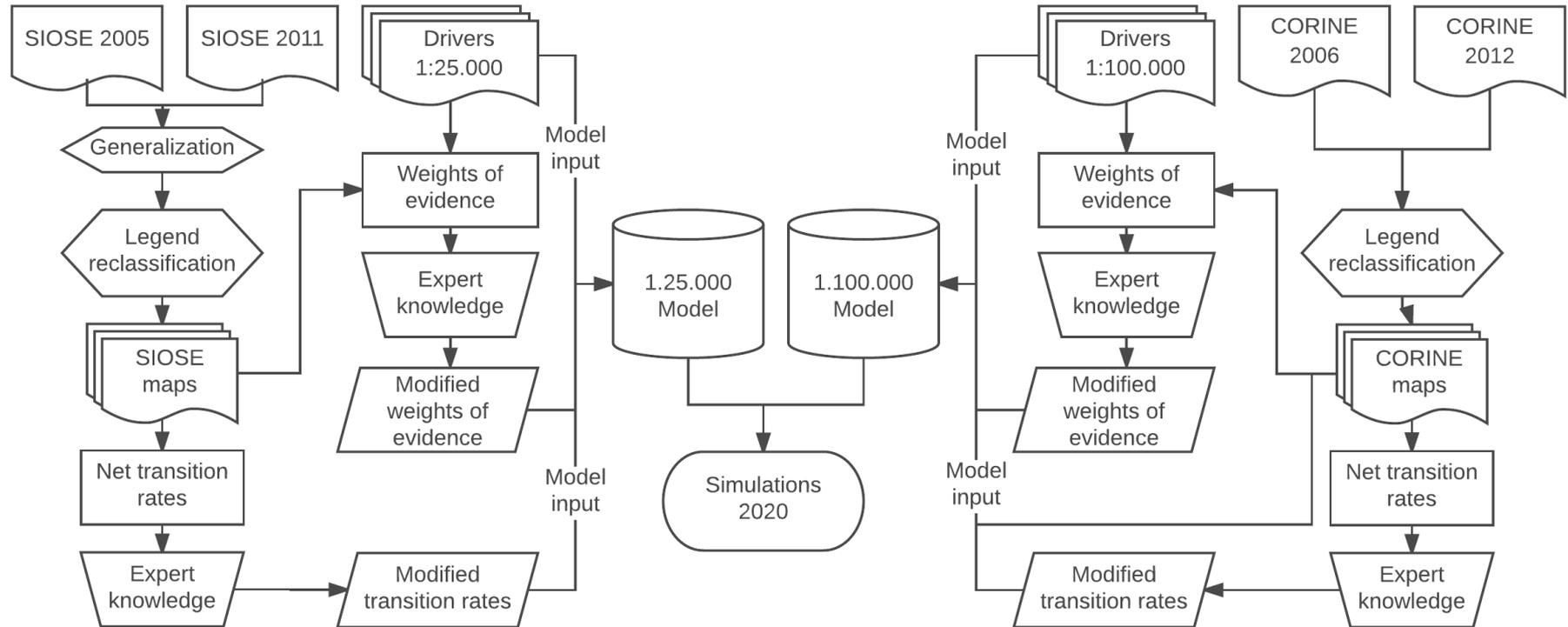
-  Motorway
-  Main road
-  Urban areas
-  Industrial areas

Elevation

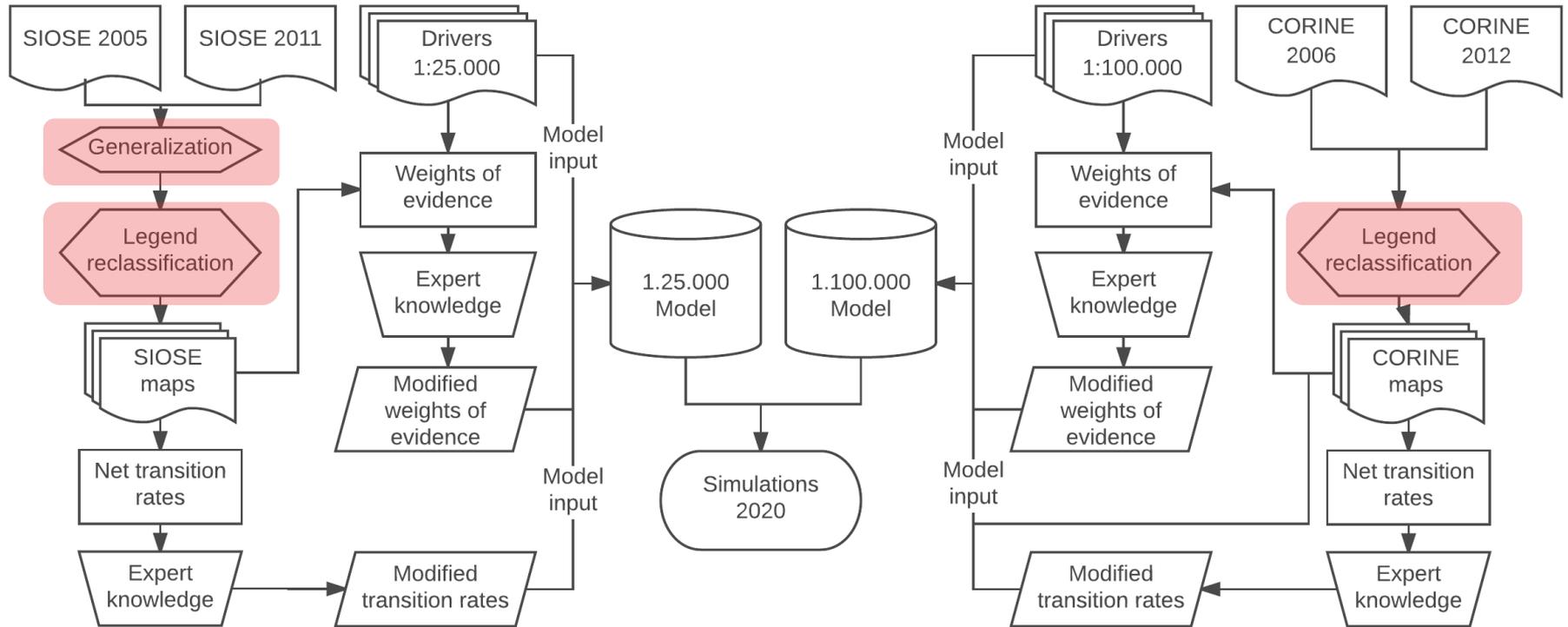


4

Method



4 Method



From a description system to a classification System Uncertainty

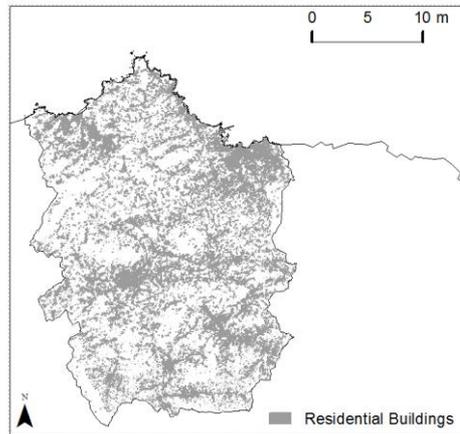
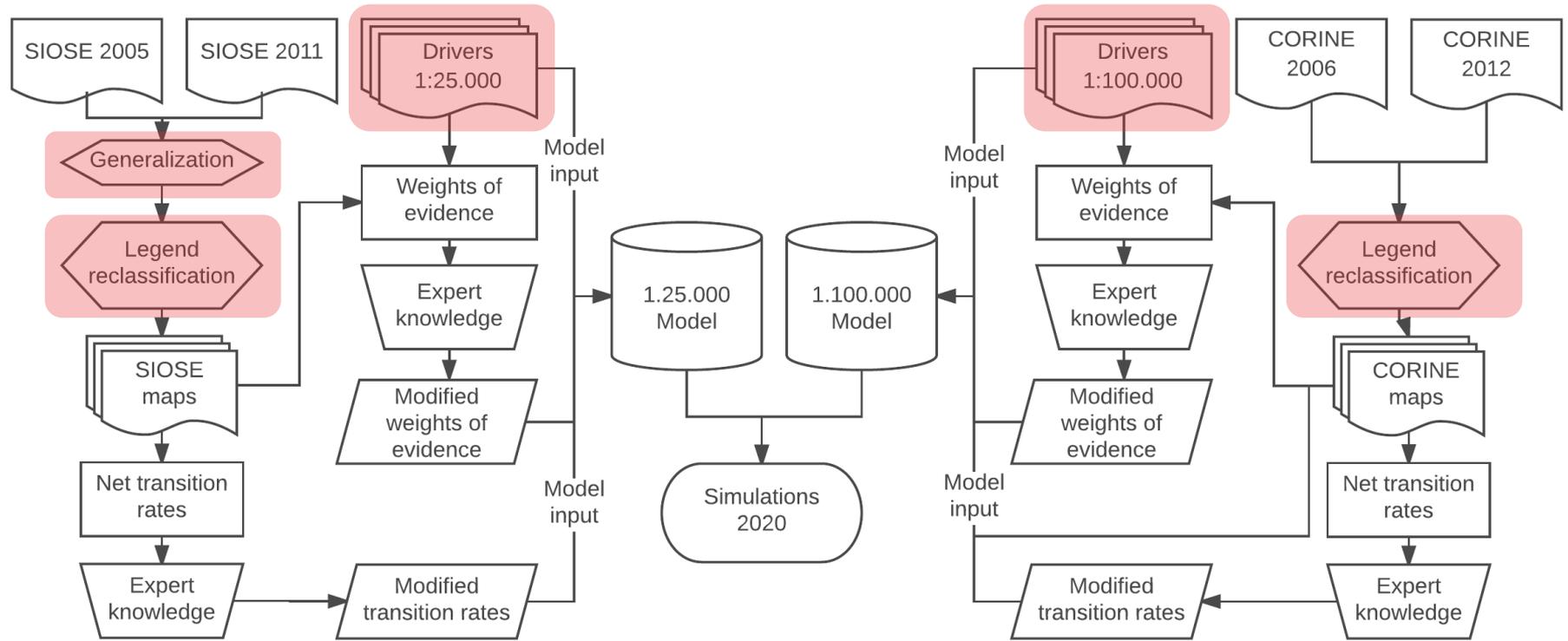
Model inputs

CORINE L3 legend simplification

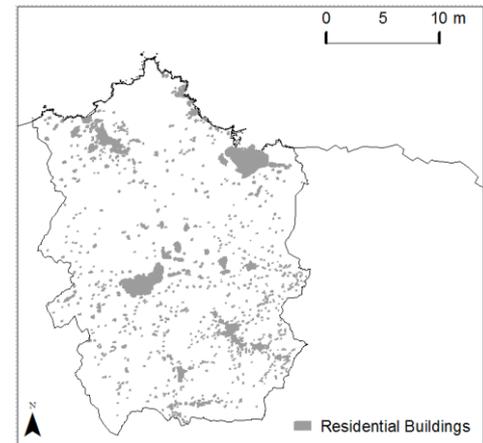
SIOSE → CORINE classes translation Uncertainty

4

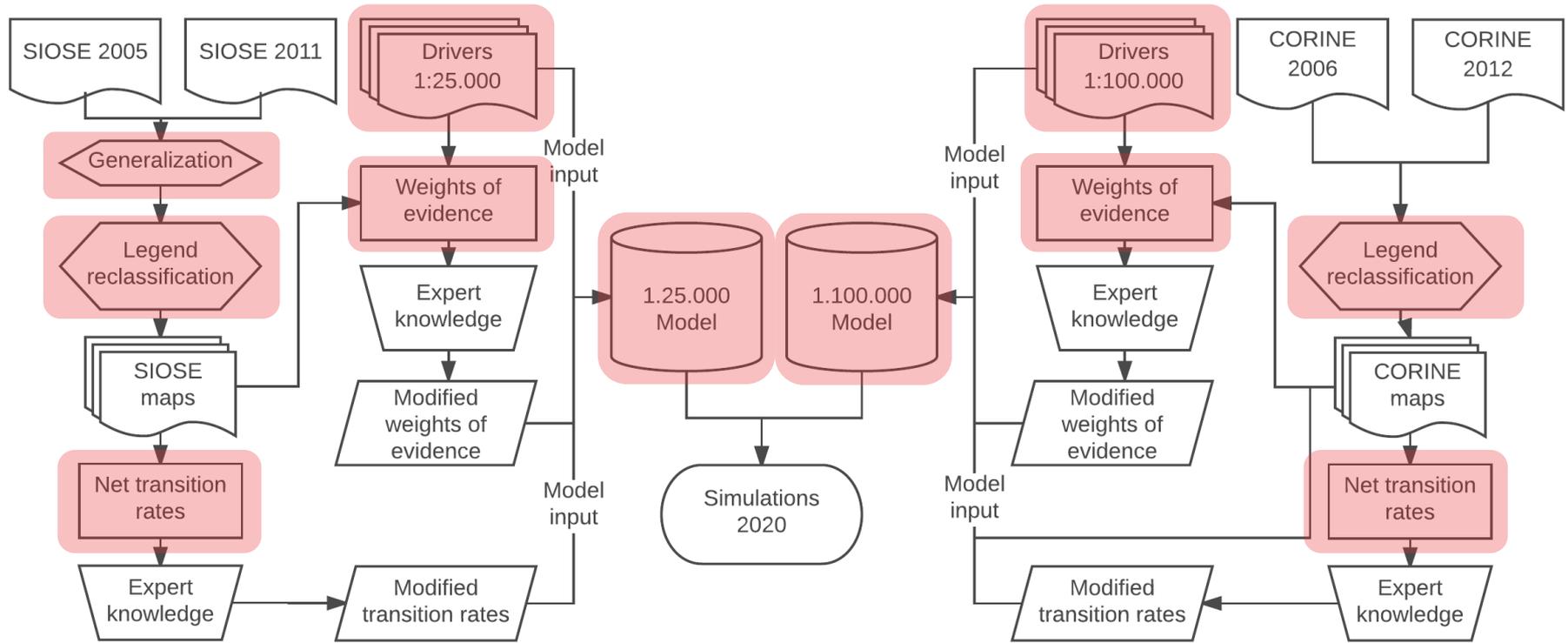
Method



Model inputs



4 Method



Transition rates: Markov Chains

Probability Maps: Weights of Evidence

Simulation: Expander and Patcher

Model calibration

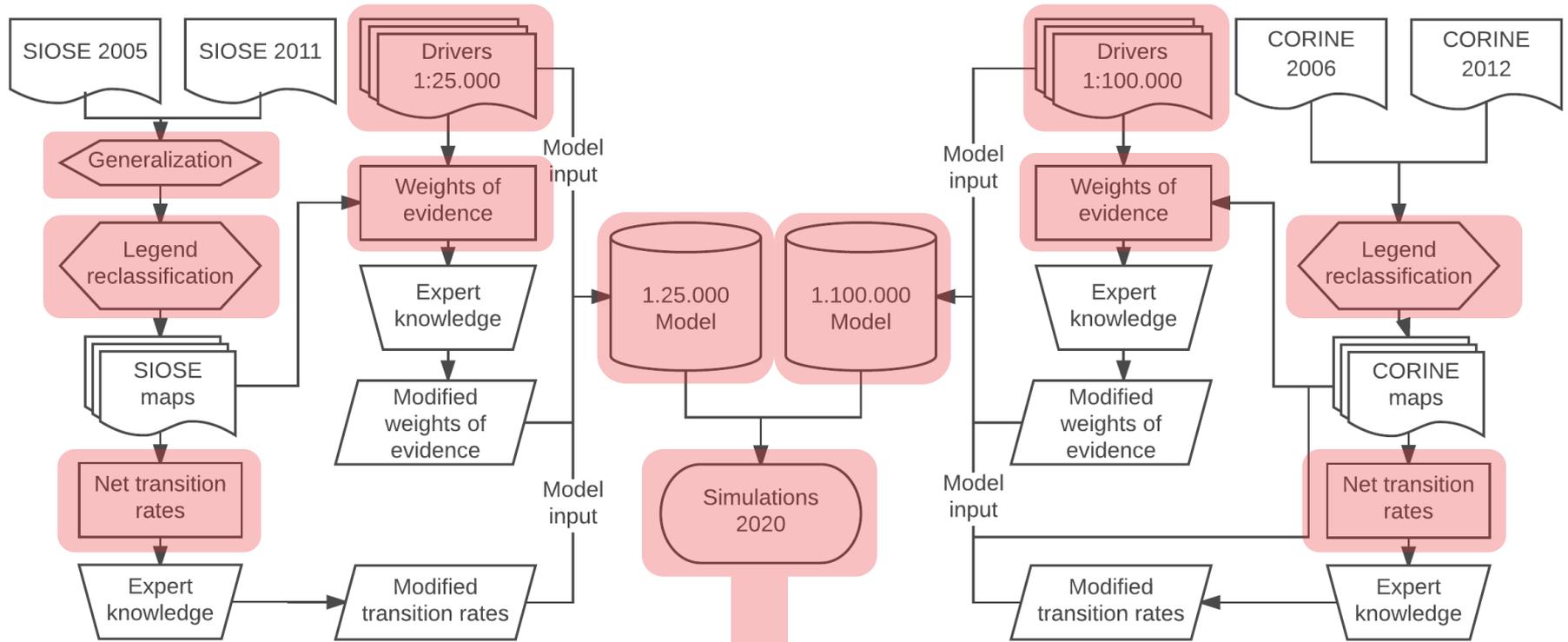


Transition rates: Markov Chains

Probability Maps: Weights of Evidence

Simulation: Expander and Patcher

4 Method



Comparison through

Pontius and Millones
(2011) matrix

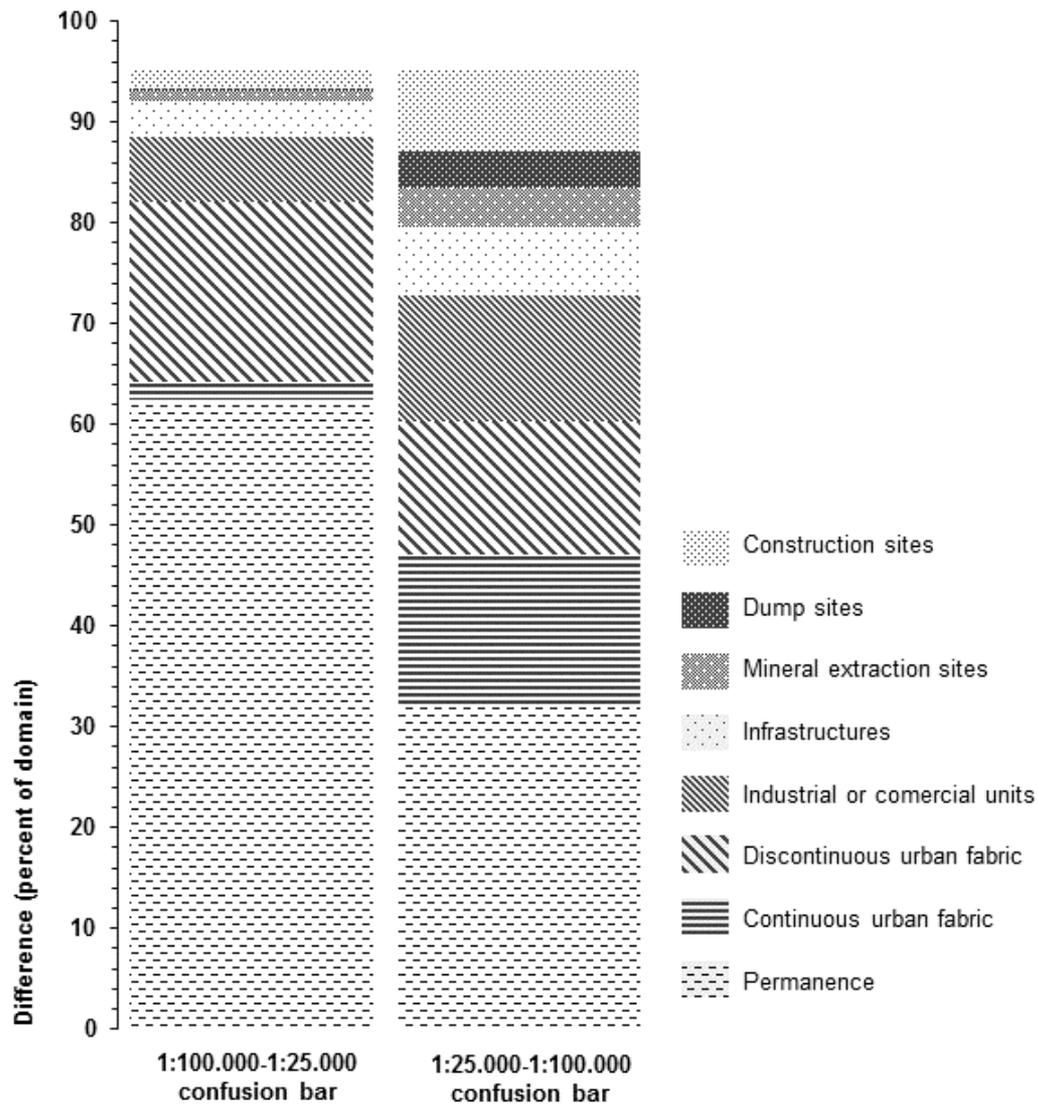
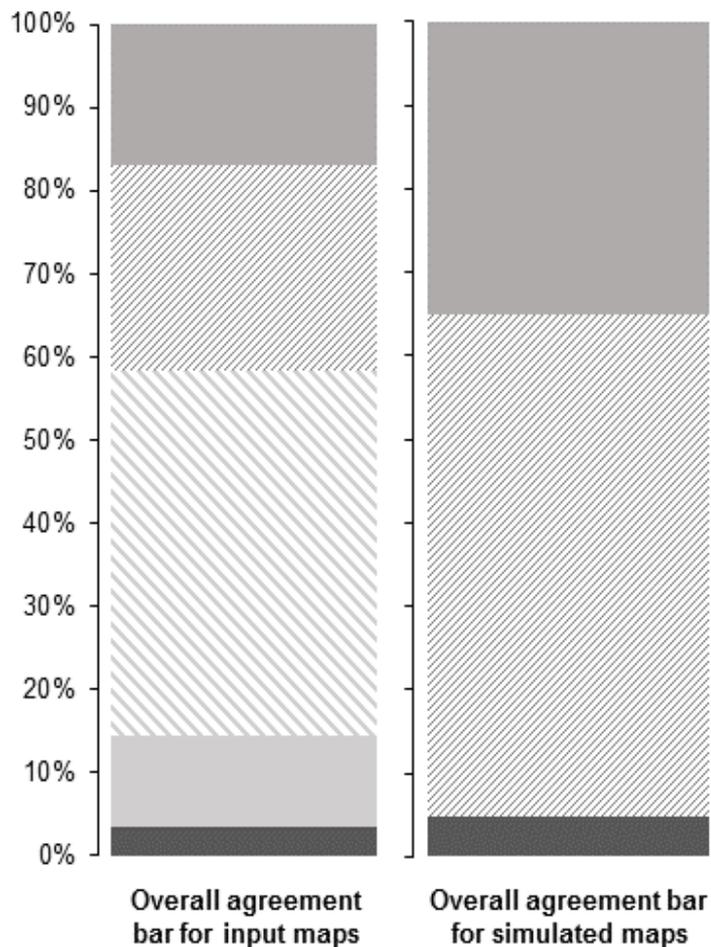
**Quantity and
allocation disagreement**

FRAGSTATS

Pattern disagreement

5 Results

Quantity and allocation disagreement



5 Results

Pattern disagreement

Simulated changes 2011-2020	Number of paths		Area-weighted mean patch area		Patch cohesion index	
	1:25	1:100	1:25	1:100	1:25	1:100
Continuous urban fabric	44	13	10.7344	3.3967	95.0723	71.0631
Discontinuous urban fabric	79	88	11.9334	16.5856	93.7738	80.4932
Industrial or commercial units	81	42	14.9641	8.1407	95.7527	79.9843
Infrastructures	15	4	14.5344	32.3644	96.4041	92.4082
Mineral extraction sites	35	5	1.9123	3.537	90.3935	72.052
Dump sites	11	4	7.7488	5.1667	94.9689	77.3581
Construction sites	118	26	3.3104	2.9085	90.2173	63.8639
Input maps changes 2005-2011	Number of paths		Area-weighted mean patch area		Patch cohesion index	
	SIOSE	CORINE	SIOSE	CORINE	SIOSE	CORINE
Continuous urban fabric	72	4	19.5006	12.5078	96.4369	86.0809
Discontinuous urban fabric	130	19	11.6396	43.5088	93.5797	92.4059
Industrial or commercial units	130	23	26.328	34.0165	95.7127	89.8172
Infrastructures	8	1	13.3087	35.75	96.6727	93.0449
Mineral extraction sites	64	2	5.3172	18.8616	92.89	88.8021
Dump sites	34	8	5.578	7.3148	93.4537	80.6492
Construction sites	95	10	37.7259	83.333	97.3597	95.4769

5 Results

Pattern disagreement

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6 Main Findings

- Input maps play an essential role in the model results. In consequence, it is very important to know their uncertainty and accuracy
- The finer the scale of the model, the bigger the quantity of changes to be simulated and the more complex the model
- The modeller has to find a balance between data detail and model complexity
- The bigger the difference between the Minimum Mapping Unit and the spatial resolution, the bigger the contrast between input maps pattern and scenarios pattern

6 Main Findings

- Validation problem: the model allocates every pixel that change whereas input maps only allocate those pixels that meet the MMU rule
- The flexibility to vary the modelled pattern depend on the scale of the input maps

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Research Project: SIGEOMOD_2020

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ACKNOWLEDGEMENTS

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